

A fluctuation-dissipation relation for the ocean subject to turbulent atmospheric forcing

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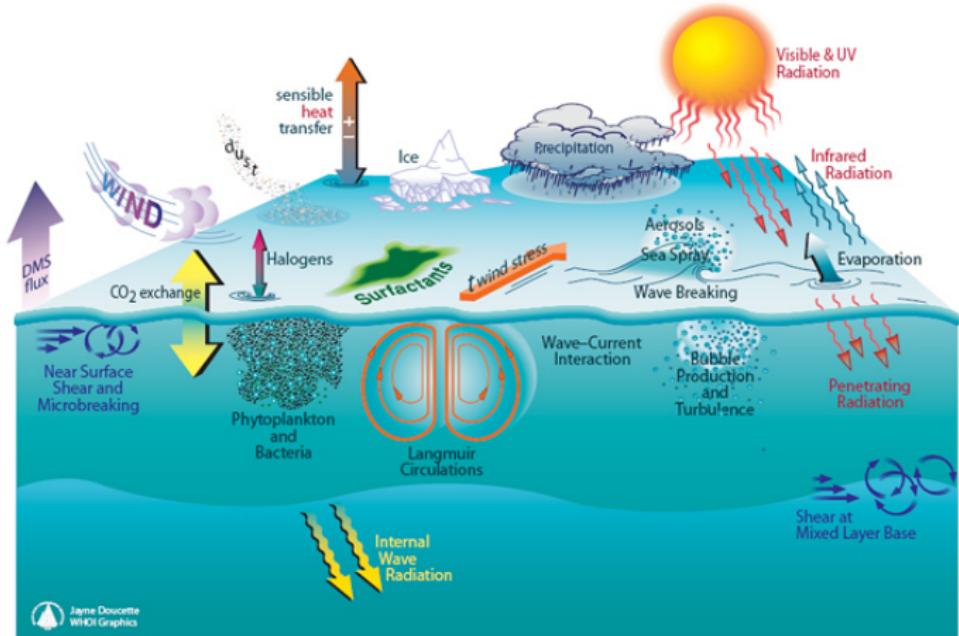
Air-Sea Interaction



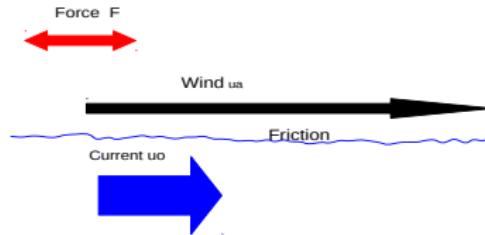


Seestück (G. Richter)

Air-Sea Interaction



Model



Parameters :

- ▶ mass ratio ocean/atmosphere: m
- ▶ friction coefficient (nonlinear): c_D

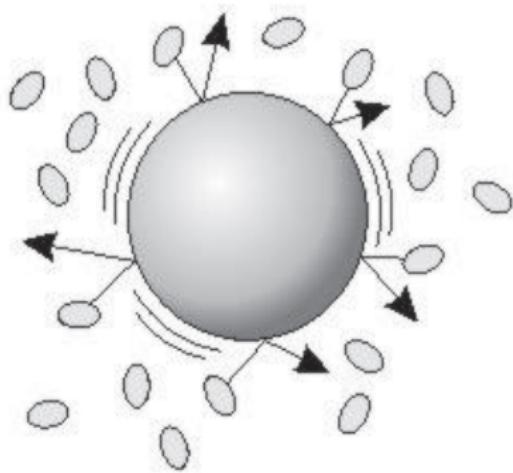


Seestück (G. Richter)



Seestück (G. Richter)

Brownian motion



Einstein relation (1905)

- ▶ macroscopic: Stoke's law : $\gamma = \frac{6\pi\eta r}{m}$
- ▶ microscopic: random walk (1D): $D = \frac{\langle x^2 \rangle}{2t} = \frac{R}{\gamma^2}$
- ▶ equipartition : $\frac{k_B T}{m} = \langle u(t)^2 \rangle = \frac{R}{\gamma}$
$$D = \frac{k_B T}{\gamma m} = \frac{R T}{N 6\pi\eta r}$$

Langevin Equation (1908)

$$m\partial_t u(t) = -m\gamma u(t) + F(t)$$

dissipation:	γ	macroscopic	systematic	constant
fluctuationn:	$F(t)$	microscopic	random	$\langle F(t) \rangle = 0$

$$\frac{m}{2}\partial_{tt}x^2 - mu^2 = -\frac{\gamma m}{2}\partial_t x^2 + xF$$

$$\frac{m}{2}\partial_{tt}\langle x^2 \rangle - m\langle u^2 \rangle = -\frac{m\gamma}{2}\partial_t \langle x^2 \rangle + \cancel{\langle xF \rangle}$$

$$\frac{m}{2}\partial_t \langle \partial_t x^2 \rangle + \frac{m\gamma}{2}\langle \partial_t x^2 \rangle = k_B T$$

$$t \gg \frac{1}{\gamma} \rightarrow \langle \partial_t x^2 \rangle = \frac{2k_B T}{m\gamma}$$

Langevin Equation, Itô calculus (1940)

$$u(0) = 0$$

$$u(t) = u(0)e^{-\gamma t} + e^{-\gamma t} \int_0^t F(t') e^{\gamma t'} dt'$$

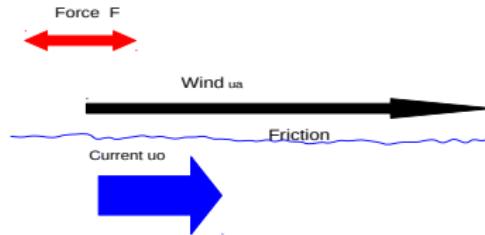
$$\langle u(t)^2 \rangle = e^{-2\gamma t} \int_0^t \int_0^t \langle F(t_1) F(t_2) \rangle e^{\gamma(t_1+t_2)} dt_2 dt_1$$

$$\langle F(t_1) F(t_2) \rangle = 2R\delta(t_2 - t_1)$$

Fluctuation dissipation relation:

$$\langle u(t)^2 \rangle = \frac{R}{\gamma}$$

Model

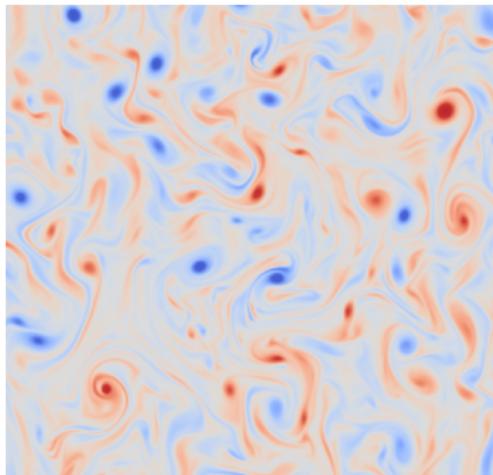


Parameters :

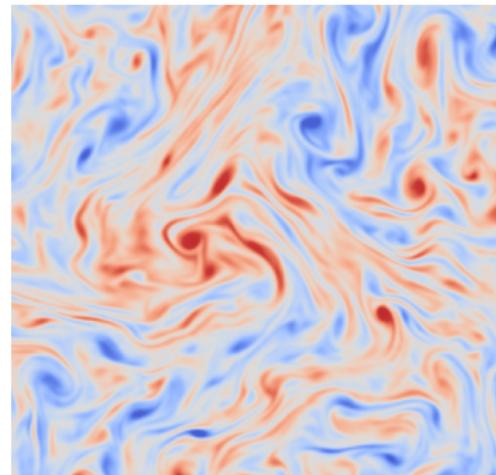
- ▶ mass ratio ocean/atmosphere: m
- ▶ friction coefficient (nonlinear): c_D

2D Turbulence

Atmos



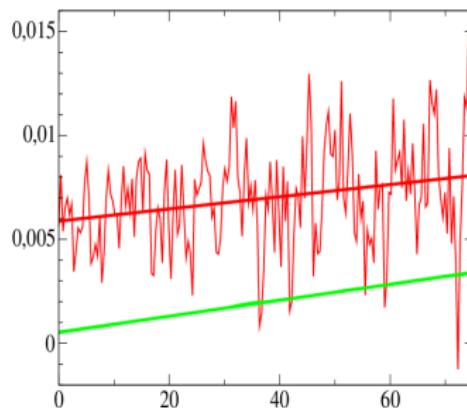
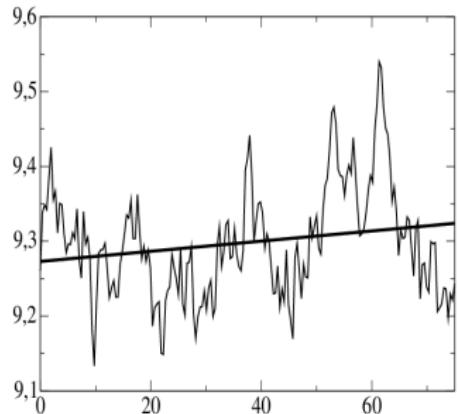
Ocean



2D Turbulence

$$\langle u_a^2 \rangle_A$$

$$\langle u_a u_o \rangle_A, \langle u_o^2 \rangle_A$$



Model



$$\partial_t u_o = -S(u_o - u_a)$$

stat. solution \leftrightarrow 2D turbulence model

Model



$$\partial_t u_a = -Sm(u_a - u_o) + F$$

$$\partial_t u_o = -S(u_o - u_a)$$

$$\frac{1}{2} \partial_t u_a^2 = -Sm(u_a^2 - u_a u_o) + F$$

$$\frac{m}{2} \partial_t u_o^2 = -Sm(u_o^2 - u_a u_o)$$

$$\partial_t e = -Sm(u_a - u_o)^2 + F$$

Linear Local Model

$$\partial_t u_s = -SMu_s + F$$

$$\partial_t u_t = F$$

$$u_s(t) = \int_0^t e^{SM(t'-t)} F(t') dt'$$

$$u_t(t) = \int_0^t F(t') dt'$$

$$u_a(t) = \frac{1}{M} (u_t + mu_s) = \frac{1}{M} \left(\int_0^t F(t') dt' + m \int_0^t e^{SM(t'-t)} F(t') dt' \right)$$

$$u_o(t) = \frac{1}{M} (u_t - u_s) = \frac{1}{M} \left(\int_0^t F(t') dt' - \int_0^t e^{SM(t'-t)} F(t') dt' \right)$$

Linear Local Model : 2nd order moments

$$\langle u_a^2 \rangle_{\Omega} = \frac{R}{M^2} \left(2t + \frac{4m}{SM} (1 - e^{-SMt}) + \frac{m^2}{SM} (1 - e^{-2SMt}) \right)$$

$$\langle u_o^2 \rangle_{\Omega} = \frac{R}{M^2} \left(2t - \frac{4}{SM} (1 - e^{-SMt}) + \frac{1}{SM} (1 - e^{-2SMt}) \right)$$

$$\langle u_a u_o \rangle_{\Omega} = \frac{R}{M^2} \left(2t + \frac{2(m-1)}{SM} (1 - e^{-SMt}) - \frac{m}{SM} (1 - e^{-2SMt}) \right).$$

For $t \gg (SM)^{-1}$:

$$\langle (u_a - u_o)^2 \rangle_{\Omega} = \frac{R}{SM}$$

$$\langle u_a^2 - u_o^2 \rangle_{\Omega} = \frac{R(M+2)}{SM^2}$$

$$\langle u_a u_o - u_o^2 \rangle_{\Omega} = \frac{R}{SM^2}$$

Fluctuation Dissipation Relation (FDR)

$$\frac{1}{2} \partial_t \langle u_o^2 \rangle_{\Omega} = S \langle u_a u_o - u_o^2 \rangle_{\Omega} = \frac{R(1 - e^{-SMt})^2}{M^2}$$

For $t \gg (SM)^{-1}$:

$$\frac{R}{M^2} = \frac{SR}{M^2} \left(2t + \frac{m-2}{SM} - 2t + \frac{3}{SM} \right)$$

Quadratic Local Model

$$\begin{aligned}\partial_t \mathbf{u}_a &= -\tilde{S}m|\mathbf{u}_s|\mathbf{u}_s + \mathbf{F} \\ \partial_t \mathbf{u}_o &= -\tilde{S}|\mathbf{u}_s|\mathbf{u}_s\end{aligned}$$

with $\mathbf{u}_s = \mathbf{u}_a - \mathbf{u}_o$, $\mathbf{u}_t = \mathbf{u}_a + m\mathbf{u}_o$.

$$\begin{aligned}\partial_t \mathbf{u}_s &= -\tilde{S}M|\mathbf{u}_s|\mathbf{u}_s + \mathbf{F} \\ \partial_t \mathbf{u}_t &= \mathbf{F}\end{aligned}$$

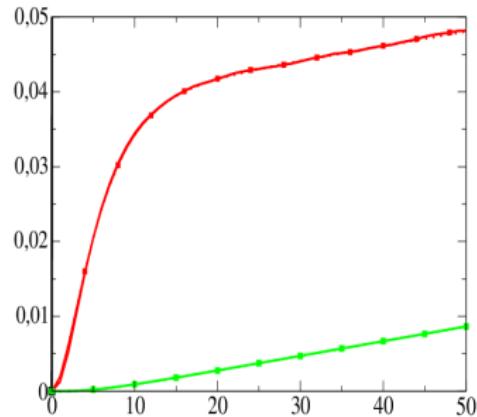
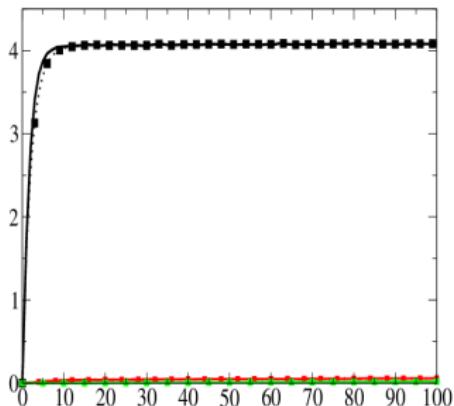
Linear Langevin eq. with eddy friction:

$$\frac{S_{\text{eddy}}}{\tilde{S}} = \frac{\langle (\mathbf{u}_s^2)^{3/2} \rangle}{\langle \mathbf{u}_s^2 \rangle^{3/2}} \langle (\mathbf{u}_s^2)^{1/2} \rangle = \left(\frac{\mu^2 2R}{\tilde{S}M} \right)^{1/3}.$$

$$\mu_{\text{Gaussian}} = \frac{\langle (\mathbf{u}_s^2)^{3/2} \rangle}{\langle \mathbf{u}_s^2 \rangle^{3/2}} = \frac{3\sqrt{\pi}}{4} \approx 1.3293404.$$

Lin. vs. Quadratic Langevin eq.

$$\langle u_a^2 \rangle_A, \langle u_o^2 \rangle_A, \langle u_a u_o \rangle_A$$



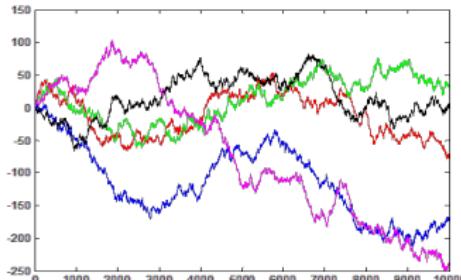
$$\mu = \frac{2\Gamma(2/3)}{3\Gamma(4/3)} \approx 1.2449; (\text{Gaussian}) = \frac{3\sqrt{\pi}}{4} \approx 1.329$$

Stochastic differential equation:
Integrating many independent realisation:

$$\partial_t u = F(u, \omega) \quad \text{with,} \quad \omega \in \Omega$$

→ measure moments :

$$\langle u^n \rangle_\Omega, \quad \langle f(u) \rangle_\Omega$$



(“Lagrangian approach”)

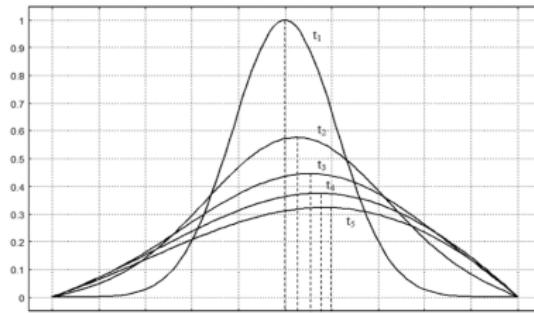
Fokker-Planck equation:

Obtain PDE for the time evolution of the pdf:

$$\partial_t P(u, t) = \partial_u \left(a(u)P(u) + \frac{1}{2} \partial_u [b(u)P(u)] \right)$$

→ solve equation if possible and obtain moments by integration:

$$\langle u^n \rangle = \int u^n dP, \quad \langle f(u) \rangle = \int f(u) dP$$



("Eulerian approach")

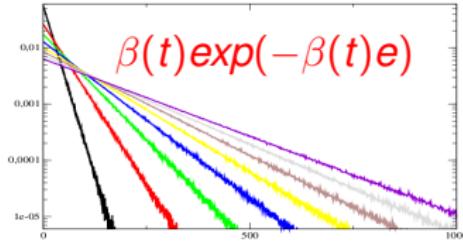
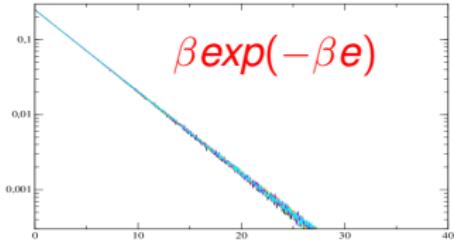
Linear model: SDE \leftrightarrow Fokker-Planck equation:

SDE:

$$\begin{aligned}\partial_t \mathbf{u}_s &= -SM\mathbf{u}_s + \mathbf{F} \\ \partial_t \mathbf{u}_t &= \mathbf{F}\end{aligned}$$

Fokker-Planck

$$\begin{aligned}\partial_t P_s &= \nabla_{uv} \cdot \left[SM\mathbf{u}_s P_s + \frac{1}{2} \nabla_{uv} P_s \right] \\ \partial_t P_t &= \frac{1}{2} \nabla_{uv} \cdot \nabla_{uv} P_t\end{aligned}$$



Non-linear model: SDE \leftrightarrow Fokker-Planck equation:

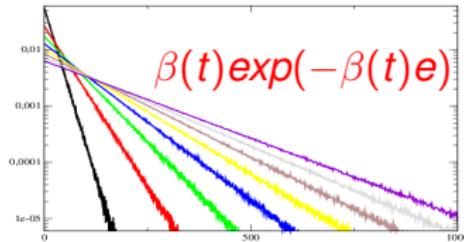
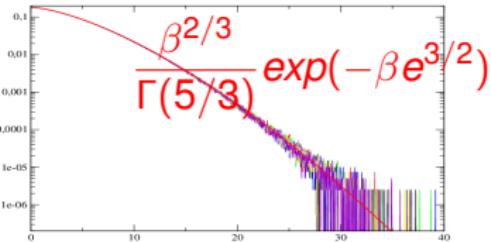
SDE:

$$\partial_t \mathbf{u}_s = - \tilde{S}M|\mathbf{u}_s|\mathbf{u}_s + \mathbf{F} \quad (1)$$

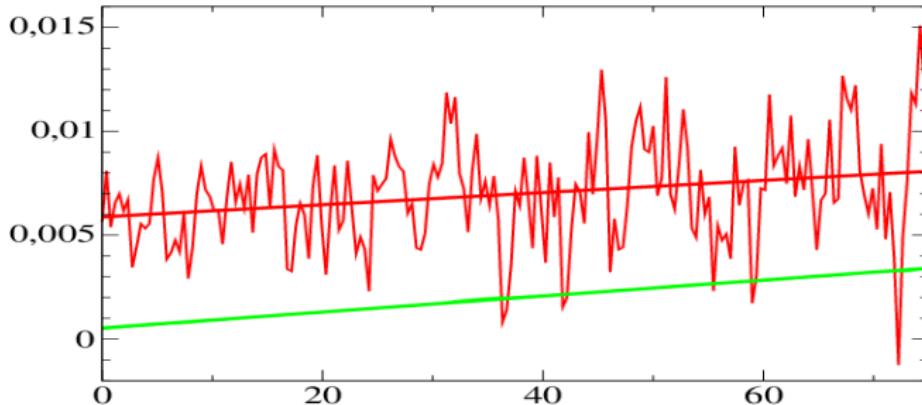
$$\partial_t \mathbf{u}_t = \mathbf{F} \quad (2)$$

Fokker-Planck

$$\begin{aligned}\partial_t P_s &= \nabla_{uv} \cdot \left[\tilde{S}M\mathbf{u}_s u_s P_s + \frac{\nu}{2} \nabla_{uv} P_s \right] \\ \partial_t P_t &= \frac{\nu}{2} \nabla_{uv} \cdot \nabla_{uv} P_s\end{aligned}$$



FDR 2D : $\langle \mathbf{u}_o^2 \rangle$, $\langle u_a u_o \rangle$



$$\frac{1}{2} \partial_t \langle u_o^2 \rangle_A = S \langle u_a u_o - u_o^2 \rangle_A$$

$$\tilde{S}_{\text{num}} = \frac{\partial_t \langle \mathbf{u}_o^2 \rangle}{2\mu_{\text{Gauss}} \sqrt{\langle (\mathbf{u}_a - \mathbf{u}_o)^2 \rangle \langle (\mathbf{u}_a \mathbf{u}_o - \mathbf{u}_o^2) \rangle}}$$
$$\frac{\tilde{S}_{\text{num}}}{\tilde{S}} = 0.92$$

Further Results

- 1) The Fluctuation Dissipation Theorem is established for linear models with white and colored forcing.

$$C(t, \Delta t) = \langle \mathbf{x}(t)\mathbf{x}^t(t + \Delta t) \rangle; \langle \mathbf{x}(t + \Delta t) \rangle = \chi(t, \Delta t)\bar{\mathbf{x}}.$$

$$C(t, \Delta t)C(t, 0)^{-1} = \chi(t, \Delta t).$$

- 2) Fluctuation Theorems are considered.

$$S_{\bar{Z}^\tau}(z) = \ln \left(\frac{f(z)}{f(-z)} \right) = \sigma \tau z,$$

$$\text{Prob}(z_1 < \bar{Z}^\tau < z_2) = \int_{z_1}^{z_2} f(z) dz$$

Conclusions

- * The ocean subject to atmospheric forcing obeys a fluctuation dissipation relation.
- * Local models (linear and quadratic) can be solved analytically.
- * Some of the results from local models can be transposed to fully 2D turbulence models.
- * The FDR can be extended to the air-sea system forced by a colored noise.
- ▶ Dissipation of non-resolved dynamics is included in models (atmosphere, ocean climate, ...) but not the fluctuations. However, fluctuation-dissipation-relations hold at all levels of the dynamics.
- ▶ Consider truly non equilibrium processes (beyond: spin-up, spin-down)